ON THE CONSTRUCTION OF NESTED SPACE-FILLING DESIGNS

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Nested space-filling designs are nested designs with attractive low-dimensional stratification. Such designs are gaining popularity in statistics, applied mathematics and engineering. Their applications include multi-fidelity computer models, stochastic optimization problems, multi-level fitting of nonparametric functions, and linking parameters. We propose methods for constructing several new classes of nested space-filling designs. These methods are based on a new group projection and other algebraic techniques. The constructed designs can accommodate a nested structure with an arbitrary number of layers and are more flexible in run size than the existing families of nested space-filling designs. As a byproduct, the proposed methods can also be used to obtain sliced space-filling designs that are appealing for conducting computer experiments with both qualitative and quantitative factors.

1. Introduction. Computer experiments are widely used in science and engineering [Fang, Li and Sudjianto (2006), Santner, Williams and Notz (2003)]. A large computer program can often be run with multiple fidelities. Qian (2009), Qian, Tang and Wu (2009) and Qian, Ai and Wu (2009) introduced the concept of *nested space-filing design* (NSFD) for running computer codes with two levels of accuracy. A pair of NSFD $L_1 \subset L_2$ are two nested designs with the small design used for the more accurate but more expensive code and the large design used for the less accurate but cheaper code. These designs have following properties:

Economy: the number of points in L_1 is smaller than the number of points in L_2;
Nested relationship: L_1 is nested within L_2, that is, $L_1 \subset L_2$;
Space-filling: the points in both L_1 and L_2 achieve uniformity in low dimensions.

The nested relationship makes it easier to adjust or calibrate the differences between the two sources.

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Multi-fidelity simulation modeling has received considerable attention over the past few years, especially in the computational fluid dynamics and finite element analysis communities where simulation costs are very high. For example, a finite element analysis code can be run with varying numbers of mesh sizes, resulting in multiple versions with three or more levels of accuracy. Multi-fidelity simulation modeling is a common practice in engineering. Examples include Dewettinck et al. (1999) for simulating a GlattGPC-1 fluidized-bed unit, Choi et al. (2008) for an aircraft design application and Molina-Cristóbal et al. (2010) for a submarine propulsion system application, among others. Specifically in Dewettinck et al. (1999), they reported a physical experiment and several associated computer models for predicting the steady-state thermodynamic operation point of a GlattGPC-1 fluidized-bed unit. One physical model ($T_{2,\exp}$) and three computer models ($T_{2,3}, T_{2,2}, T_{2,1}$) are considered. Model $T_{2,3}$, which includes adjustments for heat losses and inlet airflow, is the most accurate (i.e., producing the closest response to $T_{2,\exp}$). Model $T_{2,2}$ includes only the adjustment for heat losses, thus is the medium accurate. While model $T_{2,1}$ does not adjust for heat losses or inlet airflow and is thus the least accurate. For such experiments, it is desirable to run a multi-layer experiment using NSFDs with three or more layers, which makes it easier to model the systematic differences among the models and implies more observations are taken for less accurate experiments [cf., Haaland and Qian (2010)].

However, NSFDs with more than two layers cannot be constructed by using the methods in Qian, Tang and Wu (2009) and Qian, Ai and Wu (2009). The technical reason is the modulus projection used in Qian, Tang and Wu (2009) cannot be extended to covering more than two layers. To overcome this limitation, we present a new group-to-group projection, called the subgroup projection, in this paper and then construct several new classes of NSFDs that can accommodate nesting with an arbitrary number of layers and are more flexible in run size than existing designs of this type. The subgroup projection is based on a new decomposition of Galois fields. As far as we are aware, it is also new in algebra and may have other algebraic applications beyond design of experiments. Some families of NSFDs with more than two layers can be constructed from (t, s)-sequences with an infinite number of elements [Haaland and Qian (2010)]. In contrast, the proposed construction here is simpler and only involves a finite number of points. The constructed designs here can be used for multi-level fitting of nonparametric functions [Fasshauer (2007), Floater and Iske (1996), Haaland and Qian (2011)] and linking parameters in engineering [Husslage et al. (2003)], all of which involve nested designs with more than two layers.

The proposed constructions also give new families of sliced space-filling designs (SSFDs) which can be used to conduct computer experiments with both qualitative and quantitative factors [Han et al. (2009), Qian, Wu and Wu (2008), Zhou, Qian and Zhou (2011)]. Such computer experiments are often encountered in practice, though most literature on computer experiments assumes that all the input variables are quantitative. For example, Schmidt, Cruz and Iyengar (2005)

described a data center computer experiment which involves qualitative factors (such as diffuser location and hot-air return-vent location) and quantitative factors (such as rack power and diffuser flow rate). For conducting such an experiment, Qian and Wu (2009) proposed to use an SSFD, say $S = (S_1', \ldots, S_v')'$, with each slice S_i being associated with a level combination of the qualitative factors. Here, when collapsed over the qualitative levels, the points of the quantitative factors achieve attractive stratification and at any qualitative level, the values of the quantitative factors are spread uniformly in a low-dimensional space. An SSFD can also be used to run a computer model in batches and conduct multiple computer models [Qian (2012), Williams, Morris and Santner (2009)]. Note that the subfield projection used in Qian and Wu (2009) for constructing SSFDs is a special case of the subgroup projection proposed in this paper, thus more SSFDs can be constructed here. Moreover, the SSFDs presented in this paper can be used to conduct computer experiments with asymmetric qualitative factors.

This paper is organized as follows. Section 2 presents some useful definitions and notation. Section 3 introduces a decomposition method of Galois fields and a new algebraic projection, which play a critical role in the proposed construction methods. Sections 4–6 provide new methods for constructing nested orthogonal arrays, sliced orthogonal arrays and nested difference matrices, along with illustrative examples. Procedures for generating NSFDs from nested orthogonal arrays and SSFDs from sliced orthogonal arrays are presented in Section 7. Comparisons with existing work and concluding remarks are given in Section 8.

2. Definitions and notation. *Latin hypercube and orthogonal array-based Latin hypercube.* A *Latin hypercube* $L = (l_{ij})$ with n runs and m factors is an $n \times m$ matrix in which each column is a permutation of $0, \ldots, n - 1$ [McKay, Beckman and Conover (1979)]. Let A be an orthogonal array $OA(n, m, s, t)$ with levels $0, \ldots, s - 1$ [Hedayat, Sloane and Stufken (1999)]. If we replace the $q = n/s$ zeros in each column of A by a permutation of $0, \ldots, q - 1$, replace the q ones by a permutation of $q, \ldots, 2q - 1$, and so on, we obtain an *orthogonal array (OA)-based Latin hypercube* that achieves stratification up to t dimensions [Tang (1993)].

Sliced orthogonal array. Let A be an $OA(n_2, m, s_2, t)$. Suppose that the rows of A can be partitioned into v subarrays of n_1 rows, denoted by $A_1, \ldots, A_v$. Further suppose that there is a projection ρ that collapses the s_2 levels of A into s_1 levels with $s_2 > s_1$ and A_i becomes an $OA(n_1, m, s_1, t)$ after level-collapsing according to ρ. Then A, or more precisely $(A_1, \ldots, A_v; \rho)$, is a *sliced orthogonal array* (SOA) [Qian and Wu (2009)].

Nested orthogonal array and nested difference matrix. Qian, Tang and Wu (2009) and Qian, Ai and Wu (2009) introduced the definition of nested orthogonal array with two layers, we now extend the definition to a more general case. Suppose A_I is an $OA(n_I, m, s_I, t)$ and ρ_j for $j = 1, \ldots, I$ are a series of projections satisfying that $\rho_i(\alpha) = \rho_i(\beta)$ implies $\rho_j(\alpha) = \rho_j(\beta)$ for $j \leq i$. Then $(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$ is called a *nested orthogonal array* (NOA) with I lay-

ers, denoted by $NOA(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$, if:

   (i) A_{i-1} is nested within A_i for $2 \leq i \leq I$, that is, $A_1 \subset A_2 \subset \cdots \subset A_I$;

   (ii) $\rho_j(A_i)$ is an $OA(n_i, m, s_j, t)$ for $j \leq i$,

where $n_1 < n_2 < \cdots < n_I$ and $s_1 < s_2 < \cdots < s_I$. Given a difference matrix $D(r_I, c, s_I)$ [Bose and Bush (1952)], the concept of nested difference matrix (NDM) with I layers, denoted by $NDM(D_1, \ldots, D_I; \rho_1, \ldots, \rho_I)$, is defined in a similar fashion.

Note that the concept of NOA here is different from the one introduced in Mukerjee, Qian and Wu (2008), since the A_i for $i = 1, \ldots, I - 1$ here are not necessarily OAs before the level-collapsing but can still achieve stratification on any two dimensions. This makes the construction more flexible. For example, Figure 1 presents the bivariate projections of an $OA(64, 5, 8, 2)$ with levels $0, \ldots, 7$,
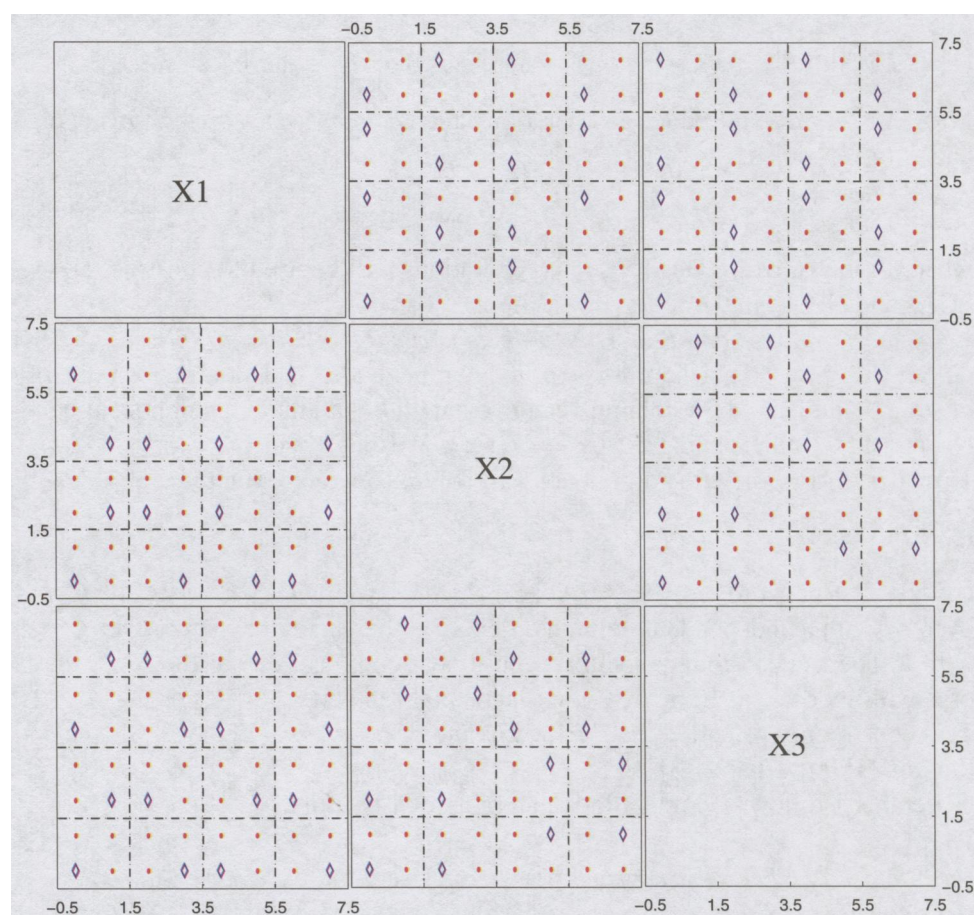

FIG. 1.   *Bivariate projections of A_1 and A_2 with $A_1 \subset A_2$, where the points labeled with both "$\diamond$" and "$\cdot$" correspond to A_2, and those labeled with "$\diamond$" correspond to A_1.*

denoted by A_2, and a 16-run subset of A_2, denoted by A_1, where the points labeled with both "⋄" and "·" correspond to A_2, and those labeled with "⋄" correspond to A_1 (for saving space, only the bivariate projections of the first three dimensions are presented here). Obviously, A_1 is not an OA, but it becomes an $OA(16, 5, 4, 2)$ with levels $0, 2, 4, 6$ after the level-collapsing according to the projection $\{0, 1\} \to 0, \{2, 3\} \to 2, \{4, 5\} \to 4, \{6, 7\} \to 6$, and the points of A_1 achieve stratification on the 4×4 grids in any two dimensions. According to Theorem 1 of Mukerjee, Qian and Wu (2008), if an $OA(N, 5, 8, 2)$ contains an $OA(16, 5, 4, 2)$, then N must satisfy $N \geq 96$, but here the larger OA only has $N = 64$ runs if the projection is used to get the smaller OA with 16 runs. Thus, in the present paper, suitable projections are critical for the definition and construction of NOAs, and the use of projections makes the construction more flexible.

Consider two matrices $A = (a_{ij}) = (a_1, \ldots, a_s)$ of order $r \times s$ and $B = (b_{ij}) = (b_1, \ldots, b_v)$ of order $u \times v$, respectively. Their *Kronecker sum* is an $ru \times sv$ matrix

$$(1) \qquad A \oplus B = (a_{ij} J + B) \qquad \text{where } J \text{ is the } u \times v \text{ matrix of ones.}$$

For $s = v$, here we introduce an operation called *column-wise Kronecker sum* of A and B, given as

$$(2) \qquad A \oplus_c B = (a_1 \oplus b_1, \ldots, a_s \oplus b_s),$$

where $\oplus$ is defined in (1). These two operations will be used to construct NOAs, SOAs and NDMs in the following sections.

Generator matrix and Rao–Hamming construction. Let $s = p^u$, $GF(p) \subseteq F_1 \subseteq GF(s)$ with $|F_1| = m$, where p is a prime number and $|F_1|$ denotes the cardinality of set F_1, and let z_j be a column vector of length k with the jth component being one and all the others being zero, $j = 1, \ldots, k$. We then obtain a $k \times (m^k - 1)/(m - 1)$ matrix Z_1 by collecting all the nonzero column vectors given by

$$(3) \qquad z = c_1 z_1 + \cdots + c_k z_k \qquad \text{where } c_j \in F_1$$

and the first nonzero entry in $(c_1, \ldots, c_k)$ is one. We call Z_1 a *generator matrix* over F_1 with k independent columns. Let Z be the generator matrix over $GF(s)$ with k independent columns and take all linear combinations of the row vectors of Z with coefficients from $GF(s)$, we then obtain an $OA(s^k, (s^k - 1)/(s - 1), s, 2)$. This construction is called the *Rao–Hamming construction* [Hedayat, Sloane and Stufken (1999), Chapter 3].

Lemma 1 follows from the Rao–Hamming construction.

LEMMA 1. *Let s be a prime power and let A be an $s^k \times k$ matrix whose rows consist of all the vectors $(x_1, \ldots, x_k)$, $x_i \in GF(s)$, $i = 1, \ldots, k$, then AZ is an $OA(s^k, (s^k - 1)/(s - 1), s, 2)$, where Z is a generator matrix over $GF(s)$ with k independent columns.*

3. A new subgroup projection. We now introduce a new projection which will play a key role in the proposed construction methods in the subsequent sections. Moreover, this new projection may have other applications in Algebra. We first present a lemma about the decomposition of Galois fields.

3.1. *Decomposition of Galois fields.* For a finite set A of size $|A|$, put its elements in an column vector V_A with zero being placed as the first entry if included. The following lemma paves the way for a new decomposition of Galois fields.

LEMMA 2. *Suppose that G is a finite Abelian group with $|G| = n$. Then there exists a decomposition of $n = p_1^{t_1} \times \cdots \times p_l^{t_l}$ and cyclic groups G_i with $|G_i| = p_i^{t_i}$ satisfying $V_G = V_{G_1} \oplus \cdots \oplus V_{G_l}$, where p_i is a prime, $G_i \subset G$ and $G_i \cap G_j = \{0\}$ for $i \neq j, i, j = 1, \ldots, l$.*

This lemma is a direct result of the fundamental theorem of finite Abelian group which states that any finite Abelian group can be decomposed as a direct sum of cyclic subgroups of prime power order [cf. Herstein (1996), Theorem 2.10.3]. Based on Lemma 2, we have the following result.

LEMMA 3. *Suppose F_3 is a Galois field $GF(p^{u_3})$ and F_1, F_2 are subgroups of F_3 under operation "$+$". If F_1 is a subgroup of F_2 under operation "$+$", then there exists a subgroup T of F_2 under operation "$+$" satisfying $V_{F_2} = V_{F_1} \oplus V_T$.*

PROOF. Suppose $|F_2| = p^{u_2}$. By Lemma 2, there exists a decomposition of $p^{u_2} = p^{t_1} \times \cdots \times p^{t_l}$ and cyclic groups G_i satisfying $V_{F_2} = V_{G_1} \oplus \cdots \oplus V_{G_l}$, where $|G_i| = p^{t_i}$, $G_i \subset F_2$ and $G_i \cap G_j = \{0\}$ for $i, j = 1, \ldots, l, i \neq j$. Since the characteristic of F_3 is the prime number p, $l = u_2$ and $t_i = 1$ for $i = 1, \ldots, l$. That is, $V_{F_2} = V_{G_1} \oplus \cdots \oplus V_{G_{u_2}}$, and $|G_i| = p, i = 1, \ldots, u_2$. As F_1 is a subgroup of F_2 under operation "$+$", without loss of generality, write $V_{F_1} = V_{G_1} \oplus \cdots \oplus V_{G_{u_1}}$, where $u_1 < u_2$. Let $V_T = V_{G_{u_1+1}} \oplus \cdots \oplus V_{G_{u_2}}$, where T is a subgroup of F_2 under operation "$+$", and $V_{F_2} = V_{F_1} \oplus V_T$. $\square$

We now introduce a new decomposition of Galois fields, serving as a basis for a new group projection. Unless otherwise specified, assume hereinafter $F_I = GF(s_I)$, F_{i-1} is a subgroup of F_i under operation "$+$" for $i = 2, \ldots, I$, and F_i has $s_i = p^{u_i}$ elements for $i = 1, \ldots, I$. Then by Lemma 3, there exist T_j's satisfying that

$$(4) \qquad V_{F_i} = V_{T_1} \oplus V_{T_2} \oplus \cdots \oplus V_{T_i}, \qquad i = 1, \ldots, I,$$

where $T_1 = F_1$ and T_j is a subgroup of F_j for $j = 2, \ldots, I$.

We introduce Algorithm 1 to perform the decomposition in (4).

ALGORITHM 1.   *Step* 1. From F_1, obtain

(5) $$V_{T_1} = V_{F_1},$$

where the first entry of V_{T_1} is zero.

Step 2. For $i = 2, \ldots, I$, from $F_{i-1} \subset F_i$ and Lemma 3, obtain T_i as a subgroup of F_i under operation "+" such that the direct sum of F_{i-1} and T_i is F_i. That is,

(6) $$V_{F_i} = V_{F_{i-1}} \oplus V_{T_i} \qquad \text{for } i = 2, \ldots, I.$$

Step 3. Combining (5) and (6) gives the decomposition in (4).

3.2. *A new subgroup projection.*   Using the above decomposition, we are now ready to propose a new group-to-group projection, which will play a key role in our construction of NSFDs. As far as we are aware, this projection is new in algebra and may have applications in other algebraic problems.

In (4), any $\gamma \in F_I$ can be uniquely expressed as

(7) $$\gamma = \beta_1 + \cdots + \beta_I, \qquad \beta_i \in T_i \text{ for } i = 1, \ldots, I.$$

Using (4) and (7), define a projection $\rho_i : F_I \to F_i$ as

(8) $$\rho_i(\gamma) = \rho_i(\beta_1 + \cdots + \beta_I) = \beta_1 + \cdots + \beta_i,$$

which maps an element in F_I to its counterpart in the subgroup F_i, $i = 1, \ldots, I$. We call this projection the *subgroup projection*.

LEMMA 4.   *For the subgroup projection and $\gamma_1, \gamma_2, \gamma \in F_I$, we have*:

(i) $\rho_i(\gamma_1 + \gamma_2) = \rho_i(\gamma_1) + \rho_i(\gamma_2)$;
(ii) $\rho_i(\rho_j(\gamma)) = \rho_{\min\{i,j\}}(\gamma) \in F_{\min\{i,j\}}$;
(iii) $\rho_i(\gamma_1) = \rho_i(\gamma_2)$ *implies* $\rho_j(\gamma_1) = \rho_j(\gamma_2)$ *for* $j \le i$;
(iv) $\rho_i(V_{F_I}) = V_{F_i} \otimes \mathbf{1}_{s_I/s_i}$,

where $\mathbf{1}_n$ denotes the nth unity vector.

Lemma 5 gives some desirable properties of the subgroup projection.

LEMMA 5.   (i) *If D is a $D(r, c, s_i)$ based on F_i, then $\rho_j(D) = (\rho_j(d_{uv}))$ is a $D(r, c, s_j)$ based on F_j for $1 \le j \le i \le I$.*

(ii) *If A is an $OA(n, m, s_i, t)$ based on F_i, then $\rho_j(A) = (\rho_j(a_{uv}))$ is an $OA(n, m, s_j, t)$ based on F_j for $1 \le j \le i \le I$.*

The subgroup projection works under a *subgroup* structure and is more general than the subfield projection introduced in Qian and Wu (2009) and the modulus projection in Qian, Tang and Wu (2009). The modulus projection, denote by φ, satisfies Lemma 5, but does not satisfy Lemma 4. Thus, the method in Qian, Tang

and Wu (2009) cannot be extended to construct NSFDs with more than two layers. For illustration, take $F_1 = GF(2)$, $F_2 = GF(2^2)$ and $F_3 = GF(2^3)$ with irreducible polynomials $g_1(x) = x + 1$, $g_2(x) = x^2 + x + 1$ and $g_3(x) = x^3 + x + 1$, respectively. For any $f(x) \in F_3$, φ gives

$$\varphi_3\big(f(x)\big) = f(x), \qquad \varphi_2\big(f(x)\big) = f_{g_2(x)}(x), \qquad \varphi_1\big(f(x)\big) = f_{g_1(x)}(x),$$

where $f_{g(x)}(x)$ denotes the residue of $f(x)$ modulo $g(x)$. Here, $\varphi_2(x^2) = \varphi_2(x + 1) = x + 1$, but $\varphi_1(x^2) = 1 \neq 0 = \varphi_1(x + 1)$, which implies φ does not satisfy Lemma 4. The truncation projection used in Qian, Ai and Wu (2009) for constructing NDMs satisfies Lemmas 4 and 5 and is a special form of the subgroup projection.

The subgroup projection will be extended to a more general group structure in Section 6.

4. Construction of NOAs and SOAs using the Rao–Hamming method for the case of $u_i < u_{i+1}$.

We now present new methods to construct NOAs with two or more layers and a sliced structure. Suppose $F_I = GF(s_I)$, $F_i = \{f(x) \in F_I |$ the degree of $f(x)$ is less than or equal to $u_i - 1\}$, $s_i = p^{u_i}$, for $i = 1, \ldots, I$, and $u_{i-1} < u_i$ for $i = 2, \ldots, I$. Then F_{i-1} is a subgroup of F_i under operation "+" for $i = 2, \ldots, I$, and (4), (7) and Lemma 4 hold.

ALGORITHM 2. *Step* 1. Let $G_i = F_i \times \cdots \times F_i = \{(\gamma_1, \ldots, \gamma_k) | \gamma_j \in F_i, j = 1, \ldots, k\}$, $i = 1, \ldots, I$. For any elements $(\gamma_{11}, \ldots, \gamma_{1k})$ and $(\gamma_{21}, \ldots, \gamma_{2k}) \in G_i$, define $(\gamma_{11}, \ldots, \gamma_{1k}) + (\gamma_{21}, \ldots, \gamma_{2k}) = (\gamma_{11} + \gamma_{21}, \ldots, \gamma_{1k} + \gamma_{2k})$, where the operation "+" is the addition on F_i.

Step 2. Let $W_i = \{(\gamma_1, \ldots, \gamma_k) | \gamma_j \in T_i, j = 1, \ldots, k\}$, which can be expressed as $\{\mathbf{0}'_k, \boldsymbol{\beta}^i_1, \ldots, \boldsymbol{\beta}^i_{(s_i/s_{i-1})^k - 1}\}$, $i = 1, \ldots, I$, where $\mathbf{0}_k$ is the kth zero vector and $s_0 = 1$.

Step 3. Suppose $G_1 = \{\mathbf{0}'_k, \boldsymbol{\eta}_1, \ldots, \boldsymbol{\eta}_{s_1^k - 1}\}$. Define an $s_1^k \times k$ matrix H_1 to be $H_1 = (\mathbf{0}_k, \boldsymbol{\eta}'_1, \ldots, \boldsymbol{\eta}'_{s_1^k - 1})'$. For $i = 2, \ldots, I$, let

$$(9) \quad H_i = \big(H'_{i-1}, [\boldsymbol{\beta}^i_1 \oplus_c H_{i-1}]', \ldots, [\boldsymbol{\beta}^i_{(s_i/s_{i-1})^k - 1} \oplus_c H_{i-1}]'\big)', \qquad i = 2, \ldots, I,$$

where $\oplus_c$ is defined in (2). Obtain

$$(10) \quad H_I = \big(H'_i, [\boldsymbol{\alpha}^i_1 \oplus_c H_i]', \ldots, [\boldsymbol{\alpha}^i_{(s_I/s_i)^k - 1} \oplus_c H_i]'\big)', \qquad i = 1, \ldots, I - 1,$$

where $\boldsymbol{\alpha}^i_j = (\alpha^i_{j1}, \ldots, \alpha^i_{jk}) \in G_I \setminus G_i$ for $j = 1, \ldots, (s_I/s_i)^k - 1$.

Step 4. Let

$$A_i = H_i C \qquad \text{for } i = 1, \ldots, I,$$

$$\boldsymbol{\gamma}^i_j = \boldsymbol{\alpha}^i_j C \qquad \text{for } i = 1, \ldots, I - 1, j = 1, \ldots, (s_I/s_i)^k - 1,$$

$$\boldsymbol{\delta}^i_j = \boldsymbol{\beta}^i_j C \qquad \text{for } i = 2, \ldots, I, j = 1, \ldots, (s_i/s_{i-1})^k - 1, \text{ and}$$

$$\Gamma^i_l = A_I\big([(l-1)s_i^k + 1] : ls_i^k\big) \qquad \text{for } i = 1, \ldots, I - 1, l = 1, \ldots, (s_I/s_i)^k,$$

where C is a generator matrix over $GF(p)$ with k independent columns, and for any matrix A, $A(u:v)$ denotes its submatrix consisting of rows u to v.

THEOREM 1.   *For the A_i's and Γ_l^i's constructed in Algorithm 2, and ρ_i's defined in Section 3.2, we have*:

(i) $A_I = (A_i', (\boldsymbol{\gamma}_1^i \oplus_c A_i)', \ldots, (\boldsymbol{\gamma}_{(s_I/s_i)^k-1}^i \oplus_c A_i)')'$, *for* $i = 1, \ldots, I-1$, $A_i = (A_{i-1}', (\boldsymbol{\delta}_1^i \oplus_c A_{i-1})', \ldots, (\boldsymbol{\delta}_{(s_i/s_{i-1})^k-1}^i \oplus_c A_{i-1})')'$, *for* $i = 2, \ldots, I$.

(ii) $(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$ *is an NOA with I layers, where $\rho_j(A_i)$ is an* $OA(s_i^k, (p^k-1)/(p-1), s_j, 2)$, *for* $1 \le j \le i \le I$;

(iii) $(\Gamma_1^i, \ldots, \Gamma_{(s_I/s_i)^k}^i; \rho_j)$ *is an SOA, for* $1 \le j \le i \le I-1$.

PROOF.   (i) It follows from the expressions of H_i's in (9) and (10), and the definition of A_i.   ·

(ii) From Lemmas 1 and 5, $\rho_j(A_i)$ is an $OA(s_i^k, (p^k-1)/(p-1), s_j, 2)$ for $j \le i$, and thus $(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$ is an NOA with I layers;

(iii) Since $\rho_j(\boldsymbol{\gamma}_l^i \oplus_c A_i) = \rho_j(\boldsymbol{\gamma}_l^i) \oplus_c \rho_j(A_i)$, then $\rho_j(\boldsymbol{\gamma}_l^i \oplus_c A_i)$ is an $OA(s_i^k, (p^k-1)/(p-1), s_j, 2)$ that can be obtained by permuting the levels of each factor in $\rho_j(A_i)$. Note that $\Gamma_1^i = A_i$ and $\Gamma_l^i = \boldsymbol{\gamma}_{l-1}^i \oplus_c A_i$ for $l > 1$, and thus $(\Gamma_1^i, \ldots, \Gamma_{(s_I/s_i)^k}^i; \rho_j)$ is an SOA, for $1 \le j \le i \le I-1$.   □

REMARK 1.   If $k > 2$ in Theorem 1, we can choose some columns from the generator matrix C to form a new matrix C^* such that the strength t of $A_I = H_I C^*$ is greater than 2. For $k = 3$ and $p = 2$, if we take

$$C^* = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix} \quad \text{from } C = \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 1 \end{pmatrix},$$

then $A_I = H_I C^*$ has strength 3. Based on such C^*'s and A_I's, the NSFDs and SSFDs generated in Section 7 will achieve stratification up to $t > 2$ dimensions.

EXAMPLE 1.   Let $s_1 = 2, s_2 = 2^2, s_3 = 2^3$, $F_1 = \{0, 1\}$, $F_2 = \{0, 1, x, x+1\}$ and $F_3 = GF(2^3) = \{0, 1, x, x+1, x^2, x^2+1, x^2+x, x^2+x+1\}$. Here, F_i is a subgroup of F_{i+1} under the operation "$+$", $i = 1, 2$. From (4),

$$\begin{cases} V_{F_2} = V_{T_1} \oplus V_{T_2}, \\ V_{F_3} = V_{T_1} \oplus V_{T_2} \oplus V_{T_3}, \end{cases}$$

with $V_{T_1} = (0, 1)'$, $V_{T_2} = (0, x)'$ and $V_{T_3} = (0, x^2)'$. For $k = 2$,

$W_1 = \{(0, 0), (0, 1), (1, 0), (1, 1)\}$,

$W_2 = \{(0, 0), (0, x), (x, 0), (x, x)\}$,

$$W_3 = \{(0,0), (0,x^2), (x^2,0), (x^2,x^2)\},$$

$$H_1 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix}, \qquad H_2 = \begin{pmatrix} H_1 \\ (0,x) \oplus_c H_1 \\ (x,0) \oplus_c H_1 \\ (x,x) \oplus_c H_1 \end{pmatrix} \quad \text{and} \quad H_3 = \begin{pmatrix} H_2 \\ (0,x^2) \oplus_c H_2 \\ (x^2,0) \oplus_c H_2 \\ (x^2,x^2) \oplus_c H_2 \end{pmatrix}.$$

Let C be a generator matrix over $GF(2)$ with two independent columns given by

$$C = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}.$$

Table 1 gives A_1, A_2, A_3 and Γ_l^i for $i = 1, 2$ and $l = 1, \ldots, 4^{3-i}$.

Suppose that ρ_1, ρ_2 and ρ_3 are defined in (8) given by

γ	0	1	x	$x+1$	x^2	x^2+1	x^2+x	x^2+x+1
$\rho_1(\gamma)$	0	1	0	1	0	1	0	1
$\rho_2(\gamma)$	0	1	x	$x+1$	0	1	x	$x+1$
$\rho_3(\gamma)$	0	1	x	$x+1$	x^2	x^2+1	x^2+x	x^2+x+1

Note that:

(i) $\rho_j(A_i)$ is an $OA(4^i, 3, 2^j, 2)$ for $1 \le j \le i \le 3$, and thus $(A_1, A_2, A_3; \rho_1, \rho_2, \rho_3)$ is an NOA with three layers;

(ii) $\rho_j(\Gamma_l^i)$ is an $OA(4^i, 3, 2^j, 2)$, and thus $(\Gamma_1^i, \ldots, \Gamma_{4^{3-i}}^i; \rho_j)$ is an SOA, where $\Gamma_l^i = A_3([4^i(l-1)+1] : 4^i l)$, for $l = 1, \ldots, 4^{3-i}$ and $1 \le j \le i \le 2$.

5. Construction of NOAs, SOAs and NDMs for the case of $u_i \mid u_{i+1}$.

Now assume $u_i < u_{i+1}$ and u_i is a factor of u_{i+1}, that is, $u_i \mid u_{i+1}$. Qian and Ai (2010) presented some constructions of NOAs with two layers for this case. Here, we provide new constructions for NOAs with two or more layers and a sliced structure, which are more general than those in Qian and Ai (2010).

5.1. Construction of NOAs and SOAs using the Rao–Hamming and Bush's methods.

THEOREM 2. *By replacing $GF(p)$ for generating the generator matrix C in Step 4 of Algorithm 2 with $F_1 = GF(s_1)$, we obtain:*

(i) $A_I = (A_i', (\gamma_1^i \oplus_c A_i)', \ldots, (\gamma_{(s_I/s_i)^k-1}^i \oplus_c A_i)')'$, *for* $i = 1, \ldots, I-1$, $A_i = (A_{i-1}', (\delta_1^i \oplus_c A_{i-1})', \ldots, (\delta_{(s_i/s_{i-1})^k-1}^i \oplus_c A_{i-1})')'$, *for* $i = 2, \ldots, I$;

(ii) $(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$ *is an NOA with I layers, where $\rho_j(A_i)$ is an $OA(s_i^k, (s_1^k-1)/(s_1-1), s_j, 2)$, for $1 \le j \le i \le I$;*

TABLE 1

The matrix A_3 in Example 1, where $A_1 = A_3(1:4)$, $A_2 = A_3(1:16)$, $\Gamma_l^1 = A_3([4(l-1)+1]:4l)$
for $l = 1, \ldots, 16$, and $\Gamma_l^2 = A_3([16(l-1)+1]:16l)$ for $l = 1, \ldots, 4$

Row	x_1	x_2	x_3	Row	x_1	x_2	x_3
1	0	0	0	33	x^2	0	x^2
2	0	1	1	34	x^2	1	x^2+1
3	1	0	1	35	x^2+1	0	x^2+1
4	1	1	0	36	x^2+1	1	x^2
5	0	x	x	37	x^2	x	x^2+x
6	0	$x+1$	$x+1$	38	x^2	$x+1$	x^2+x+1
7	1	x	$x+1$	39	x^2+1	x	x^2+x+1
8	1	$x+1$	x	40	x^2+1	$x+1$	x^2+x
9	x	0	x	41	x^2+x	0	x^2+x
10	x	1	$x+1$	42	x^2+x	1	x^2+x+1
11	$x+1$	0	$x+1$	43	x^2+x+1	0	x^2+x+1
12	$x+1$	1	x	44	x^2+x+1	1	x^2+x
13	x	x	0	45	x^2+x	x	x^2
14	x	$x+1$	1	46	x^2+x	$x+1$	x^2+1
15	$x+1$	x	1	47	x^2+x+1	x	x^2+1
16	$x+1$	$x+1$	0	48	x^2+x+1	$x+1$	x^2
17	0	x^2	x^2	49	x^2	x^2	0
18	0	x^2+1	x^2+1	50	x^2	x^2+1	1
19	1	x^2	x^2+1	51	x^2+1	x^2	1
20	1	x^2+1	x^2	52	x^2+1	x^2+1	0
21	0	x^2+x	x^2+x	53	x^2	x^2+x	x
22	0	x^2+x+1	x^2+x+1	54	x^2	x^2+x+1	$x+1$
23	1	x^2+x	x^2+x+1	55	x^2+1	x^2+x	$x+1$
24	1	x^2+x+1	x^2+x	56	x^2+1	x^2+x+1	x
25	x	x^2	x^2+x	57	x^2+x	x^2	x
26	x	x^2+1	x^2+x+1	58	x^2+x	x^2+1	$x+1$
27	$x+1$	x^2	x^2+x+1	59	x^2+x+1	x^2	$x+1$
28	$x+1$	x^2+1	x^2+x	60	x^2+x+1	x^2+1	x
29	x	x^2+x	x^2	61	x^2+x	x^2+x	0
30	x	x^2+x+1	x^2+1	62	x^2+x	x^2+x+1	1
31	$x+1$	x^2+x	x^2+1	63	x^2+x+1	x^2+x	1
32	$x+1$	x^2+x+1	x^2	64	x^2+x+1	x^2+x+1	0

(iii) $(\Gamma_1^i, \ldots, \Gamma_{(s_I/s_i)^k}^i; \rho_j)$ *is an SOA, for* $1 \le j \le i \le I - 1$.

REMARK 2. Similarly, as discussed in Remark 1, if $k > 2$ in Theorem 2, then we can choose some columns of the generator matrix C to form a new matrix C^* such that $A_I = H_I C^*$ has a strength greater than 2.

For $s_1 \geq k - 1$ and $F_1 = \{v_1, \ldots, v_{s_1}\}$, if we replace the generator matrix C in Theorem 2 by the following matrix:

$$(11) \qquad V = \begin{pmatrix} 1 & 1 & \cdots & 1 & 0 \\ v_1 & v_2 & \cdots & v_{s_1} & 0 \\ v_1^2 & v_2^2 & \cdots & v_{s_1}^2 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ v_1^{k-2} & v_2^{k-2} & \cdots & v_{s_1}^{k-2} & 0 \\ v_1^{k-1} & v_2^{k-1} & \cdots & v_{s_1}^{k-1} & 1 \end{pmatrix},$$

then we can generate new NOAs and SOAs with strength k based on Bush's method [Hedayat, Sloane and Stufken (1999), Chapter 3]. For most cases, $k > 2$, and the related NSFDs and SSFDs will achieve stratification up to $k > 2$ dimensions.

THEOREM 3.   *If in Theorem 2, C is replaced by the V in (11), then:*

(i) A_i *is an* $OA(s_i^k, s_1 + 1, s_i, k)$, *for* $i = 1, \ldots, I$;

(ii) $A_I = (A_i', (\boldsymbol{\gamma}_1^i \oplus_c A_i)', \ldots, (\boldsymbol{\gamma}_{(s_I/s_i)^k-1}^i \oplus_c A_i)')'$, *for* $i = 1, \ldots, I - 1$, $A_i = (A_{i-1}', (\boldsymbol{\delta}_1^i \oplus_c A_{i-1})', \ldots, (\boldsymbol{\delta}_{(s_i/s_{i-1})^k-1}^i \oplus_c A_{i-1})')'$, *for* $i = 2, \ldots, I$;

(iii) $(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$ *is an NOA with I layers, where $\rho_j(A_i)$ is an* $OA(s_i^k, s_1 + 1, s_j, k)$, *for* $1 \leq j \leq i \leq I$;

(iv) $(\Gamma_1^i, \ldots, \Gamma_{(s_I/s_i)^k}^i; \rho_j)$ *is an SOA, for* $1 \leq j \leq i \leq I - 1$.

5.2. *Construction of NOAs and SOAs from NDMs.* We now propose a new approach for constructing NOAs and SOAs from NDMs. Theorem 4 follows from Lemmas 4 and 5.

THEOREM 4.   *Let A be an $OA(n, m, s_I, 2)$, and*

$$V = V_{T_I} \oplus V_{T_{I-1}} \oplus \cdots \oplus V_{T_1}, \qquad D = V V_{T_1}',$$

$$\Delta_l^i = D([(l-1)s_i + 1] : l s_i) \qquad for\ l = 1, \ldots, s_I/s_i, i = 1, \ldots, I-1,$$

$$\Delta(i, k) = ((\Delta_1^i)', \ldots, (\Delta_k^i)')' \qquad for\ k = 1, \ldots, s_I/s_i - 1, i = 1, \ldots, I-1.$$

Then for $1 \leq j \leq i \leq I, k = 1, \ldots, s_I/s_i - 1$ *and* $l = 1, \ldots, s_I/s_i$, *we have:*

(i) D *is a* $D(s_I, s_1, s_I)$, Δ_1^i *is a* $D(s_i, s_1, s_i)$, *and* $A \oplus D$ *is an* $OA(ns_I, ms_1, s_I, 2)$;

(ii) $\rho_j(\Delta_l^i)$ *is a* $D(s_i, s_1, s_j)$ *based on F_j, $\rho_j(\Delta(i, k))$ is a $D(ks_i, s_1, s_j)$ based on F_j, $(\Delta(i, k), D; \rho_j, \rho_I)$ is an NDM with two layers, and $(\Delta_1^1, \ldots, \Delta_1^{I-1}, D; \rho_1, \ldots, \rho_I)$ is an NDM with I layers;*

(iii) $\rho_j(A \oplus \Delta_l^i)$ is an $OA(ns_i, ms_1, s_j, 2)$, $(A \oplus \Delta_1^i, \ldots, A \oplus \Delta_{s_I/s_i}^i; \rho_j)$ is an SOA, $(A \oplus \Delta(i,k), A \oplus D; \rho_j, \rho_I)$ is an NOA with two layers, and $(A \oplus \Delta_1^1, \ldots, A \oplus \Delta_1^{I-1}, A \oplus D; \rho_1, \ldots, \rho_I)$ is an NOA with I layers.

6. Construction of NOAs, SOAs and NDMs with more general numbers of levels.

The constructed NOAs, SOAs and NDMs so far have prime power numbers of levels. We now present constructions with more general numbers of levels by using the operation column-wise Kronecker sum defined in (2).

Let $\Psi_i = \{\psi_1, \ldots, \psi_{s_i}\}$ be a group with positive integer s_i, and

$$(12) \qquad \Omega_i = \{\psi_j \omega^{i-1} | \psi_j \in \Psi_i, \omega \text{ is an indeterminate}, j = 1, \ldots, s_i\},$$

for $i = 1, \ldots, I$. For any entries $\psi_{j_1}, \psi_{j_2} \in \Psi_i$, there exists $\psi_{j_3} \in \Psi_i$ such that $\psi_{j_1} + \psi_{j_2} = \psi_{j_3}$ and define

$$\psi_{j_1} \omega^{i-1} + \psi_{j_2} \omega^{i-1} = \psi_{j_3} \omega^{i-1},$$

which implies Ω_i forms a group. Let, for $i = 1, \ldots, I$,

$$(13) \quad F_i = \{\psi_{l_0} + \psi_{l_1}\omega + \cdots + \psi_{l_{i-1}}\omega^{i-1} | \psi_{l_b} \in \Psi_{b+1}, b = 0, \ldots, i-1\},$$

and for any elements $\alpha = \psi_{l_0} + \psi_{l_1}\omega + \cdots + \psi_{l_{i-1}}\omega^{i-1}$ and $\beta = \psi_{l_0}^* + \psi_{l_1}^*\omega + \cdots + \psi_{l_{i-1}}^*\omega^{i-1} \in F_i$, define

$$\alpha + \beta = (\psi_{l_0} + \psi_{l_1}\omega + \cdots + \psi_{l_{i-1}}\omega^{i-1}) + (\psi_{l_0}^* + \psi_{l_1}^*\omega + \cdots + \psi_{l_{i-1}}^*\omega^{i-1})$$

$$= (\psi_{l_0} + \psi_{l_0}^*) + (\psi_{l_1} + \psi_{l_1}^*)\omega + \cdots + (\psi_{l_{i-1}} + \psi_{l_{i-1}}^*)\omega^{i-1}.$$

Then $F_i = \sigma(\bigcup_{l=1}^i \Omega_l)$ is a group. Note that F_i is a subgroup of F_{i+1} and thus (4) and (7) hold, where $T_i = \Omega_i$. Now express the projection in (8) as

$$(14) \qquad \rho_i(\gamma) = \psi_{l_0} + \psi_{l_1}\omega + \cdots + \psi_{l_{i-1}}\omega^{i-1},$$

$$\gamma = \psi_{l_0} + \psi_{l_1}\omega + \cdots + \psi_{l_{I-1}}\omega^{I-1} \in F_I.$$

Hence, Lemmas 4 and 5 also hold under this projection.

6.1. Construction of NOAs and SOAs with more general number of levels.
First, we propose a method for constructing SOAs and NOAs with two layers via the column-wise Kronecker sum.

THEOREM 5. Let A_i be an $OA(n_i, m, s_i, t)$ based on Ω_i for $i = 1, 2$. Let $B = A_2 \oplus_c A_1$, and denote $B = (B_1', \ldots, B_{n_2}')'$, where $B_i = B([(i-1)n_1+1]:in_1)$, $i = 1, \ldots, n_2$. Then:

(i) B is an $OA(n_1 n_2, m, s_1 s_2, t)$ based on $F_2 = \sigma(\Omega_1 \cup \Omega_2)$;

(ii) B or $(B_1, \ldots, B_{n_2}; \rho_1)$ is an SOA, where $\rho_1(B_i)$ is an $OA(n_1, m, s_1, t)$ for $i = 1, \ldots, n_2$;

(iii) $(B^l, B; \rho_1, \rho_2)$ *is an NOA with two layers, where* $B^l = (B_1', \ldots, B_l')'$ *and* $\rho_1(B^l)$ *is an* $OA(ln_1, m, s_1, t)$ *for* $l = 1, \ldots, n_2 - 1$.

PROOF. Denote $A_1 = (a_1^1, \ldots, a_m^1) = (a^1(i, j))$ and $A_2 = (a_1^2, \ldots, a_m^2) = (a^2(i, j))$.

(i) For any t columns $(b_{i_1}, \ldots, b_{i_t})$ of B, $b_{i_j} = a_{i_j}^2 \oplus a_{i_j}^1$. Then for any t-tuple $(\alpha_1, \ldots, \alpha_t)$ in these columns, $\alpha_j = \gamma_j + \beta_j \in F_2$ with $\gamma_j \in \Omega_2, \beta_j \in \Omega_1$ for $j = 1, \ldots, t$. Since A_1 is an $OA(n_1, m, s_1, t)$ and A_2 is an $OA(n_2, m, s_2, t)$, then $(\beta_1, \ldots, \beta_t)$ occurs n_1/s_1^t times in $(a_{i_1}^1, \ldots, a_{i_t}^1)$, and $(\gamma_1, \ldots, \gamma_t)$ occurs n_2/s_2^t times in $(a_{i_1}^2, \ldots, a_{i_t}^2)$. Thus, $(\gamma_1 + \beta_1, \ldots, \gamma_t + \beta_t) = (\alpha_1, \ldots, \alpha_t)$ occurs $n_1 n_2/(s_1 s_2)^t$ times in $(b_{i_1}, \ldots, b_{i_t})$, which implies B is an $OA(n_1 n_2, m, s_1 s_2, t)$ based on F_2.

(ii) Note that $B_i = (a^2(i, 1), \ldots, a^2(i, m)) \oplus_c A_1$ and

$$\rho_1(B_i) = (\rho_1(a^2(i, 1)), \ldots, \rho_1(a^2(i, m))) \oplus_c A_1.$$

Clearly, $\rho_1(B_i)$ is an $OA(n_1, m, s_1, t)$ that can be obtained by permuting levels of each factor in A_1 and $(B_1, \ldots, B_{n_2}; \rho_1)$ is an SOA.

(iii) The result in (ii) implies that $(B^l, B; \rho_1, \rho_2)$ is an NOA with two layers. □

EXAMPLE 2. Let $Z_s = \{0, \ldots, s-1\}$, $s_1 = 6$, $s_2 = 2$, $\Psi_1 = Z_6$ and $\Psi_2 = Z_2$, then $\Omega_1 = Z_6$, $\Omega_2 = \{0, \omega\}$, $F_1 = Z_6$ and $F_2 = \{Z_6, \omega + Z_6\}$. By (4) and (14), $V_{F_2} = V_{\Omega_1} \oplus V_{\Omega_2}$ and

$\gamma \in F_2$	0	1	2	3	4	5	ω	$\omega+1$	$\omega+2$	$\omega+3$	$\omega+4$	$\omega+5$
$\rho_1(\gamma)$	0	1	2	3	4	5	0	1	2	3	4	5
$\rho_2(\gamma)$	0	1	2	3	4	5	ω	$\omega+1$	$\omega+2$	$\omega+3$	$\omega+4$	$\omega+5$

Let A_1 be an $OA(36, 3, 6, 2)$ based on Ω_1 and A_2 be an $OA(4, 3, 2, 2)$ based on Ω_2, which are listed in Table 2.

Then $B = A_2 \oplus_c A_1 = (B_1', \ldots, B_4')'$ satisfies:

(i) B is an $OA(144, 3, 12, 2)$ based on F_2;

TABLE 2
The arrays A_1 and A_2 in Example 2

A_1'																																				A_2'			
0	0	0	0	0	0	1	1	1	1	1	1	2	2	2	2	2	2	3	3	3	3	3	3	4	4	4	4	4	4	5	5	5	5	5	5	0	0	ω	ω
0	1	2	3	4	5	0	1	2	3	4	5	0	1	2	3	4	5	0	1	2	3	4	5	0	1	2	3	4	5	0	1	2	3	4	5	0	ω	0	ω
5	3	4	1	2	0	3	2	1	0	4	5	0	5	2	4	3	1	2	1	3	5	0	4	1	4	0	3	5	2	4	0	5	2	1	3	0	ω	ω	0

(ii) $\rho_1(B_i)$ is an $OA(36, 3, 6, 2)$ for $i = 1, \ldots, 4$, that is, $(B_1, \ldots, B_4; \rho_1)$ is an SOA;

(iii) $\rho_1(B^l)$ is an $OA(36l, 3, 6, 2)$, that is, $(B^l, B; \rho_1, \rho_2)$ is an NOA with two layers, where $B^l = (B'_1, \ldots, B'_l)'$ for $l = 1, 2, 3$.

Since an $OA(s^2, s + 1, s, 2)$ exists for any prime power s, Theorem 5 gives the following corollary.

COROLLARY 1. *For a prime power s_1 and $s_2 = s_1^2$, there exists an SOA* $(B_1, \ldots, B_{s_2}; \rho)$*, where $B = (B'_1, \ldots, B'_{s_2})'$ is an $OA(s_2^2, s_1 + 1, s_2, 2)$ and $\rho(B_j)$ is an $OA(s_2, s_1 + 1, s_1, 2)$ for $j = 1, \ldots, s_2$.*

REMARK 3. For a prime power s_1 and $s_2 = s_1^2$, Xu, Haaland and Qian (2011) constructed a special SOA $(B_1, \ldots, B_{s_2}; \rho)$ based on *doubly orthogonal Sudoku Latin squares*, where $B = (B'_1, \ldots, B'_{s_2})'$ is an $OA(s_2^2, s_1, s_2, 2)$, $\rho(B_j)$ is an $OA(s_2, s_1, s_1, 2)$ and each B_j has maximum stratification in one-dimension in the sense there are s_2 different levels in each column of B_j, for $j = 1, \ldots, s_2$. In contrast, B_j in Corollary 1 does not achieve maximum stratification in one-dimension, since there are only s_1 different levels in each column. But the SOAs obtained here have one more column compared with that of Xu, Haaland and Qian (2011). In addition, more SOAs can be constructed through Theorem 5 for general s_1 and s_2.

Next, we generalize Theorem 5 to construct SOAs and NOAs with more than two layers.

COROLLARY 2. *Let A_i be an $OA(n_i, m, s_i, t)$ based on Ω_i and $B_i = A_i \oplus_c \cdots \oplus_c A_1$ for $i = 1, \ldots, I$. Suppose $\Gamma_l^i = B_I([(l-1)n_1 \cdots n_i + 1] : ln_1 \cdots n_i)$ for $l = 1, \ldots, n_{i+1} \cdots n_I$ and $i = 1, \ldots, I - 1$. Then:*

(i) *$(B_1, \ldots, B_I; \rho_1, \ldots, \rho_I)$ is an NOA with I layers, where $\rho_j(B_i)$ is an* $OA(n_1 \cdots n_i, m, \prod_{l=1}^{j} s_l, t)$ *for $1 \leq j \leq i \leq I$;*

(ii) *$(\Gamma_1^i, \ldots, \Gamma_{n_{i+1} \cdots n_I}^i; \rho_j)$ is an SOA for $1 \leq j \leq i \leq I - 1$, where $\rho_j(\Gamma_l^i)$ is an* $OA(n_1 \cdots n_i, m, \prod_{l=1}^{j} s_l, t)$ *for $l = 1, \ldots, n_{i+1} \cdots n_I$.*

6.2. *Construction of NDMs with more general numbers of levels.* We present a method for constructing NDMs via the column-wise Kronecker sum. Similar to Corollary 2, we have the following result.

THEOREM 6. *Let D_i be a $D(r_i, c, s_i)$ based on Ω_i and $E_i = D_i \oplus_c \cdots \oplus_c D_1$ for $i = 1, \ldots, I$. Suppose*

$$\Delta_l^i = E_I([(l-1)r_1 \cdots r_i + 1] : lr_1 \cdots r_i),$$

for $l = 1, \ldots, r_{i+1} \cdots r_I$ and $i = 1, \ldots, I - 1$. Then:

(i) $(E_1, \ldots, E_I; \rho_1, \ldots, \rho_I)$ is an NDM with I layers, where $\rho_j(E_i)$ is a $D(r_1 \cdots r_i, c, \prod_{l=1}^{j} s_l)$ for $1 \le j \le i \le I$;

(ii) $\rho_j(\Delta_l^i)$ is a $D(r_1 \cdots r_i, c, \prod_{l=1}^{j} s_l)$ for $1 \le j \le i \le I - 1$ and $l = 1, \ldots, n_{i+1} \cdots n_I$.

EXAMPLE 3. Let $Z_s = \{0, \ldots, s-1\}$, $s_1 = 4$, $s_2 = 3$, $s_3 = 2$, $\Psi_1 = GF(4)$, $\Psi_2 = Z_3$ and $\Psi_3 = Z_2$ Then from (12), (13) and (14), $\Omega_1 = GF(4)$, $\Omega_2 = \{0, \omega, 2\omega\}$, $\Omega_3 = \{0, \omega^2\}$, $F_1 = GF(4)$, $F_2 = \{k\omega + F_1, k \in Z_3\}$, $F_3 = \{k\omega^2 + F_2, k \in Z_2\}$, and for any $\gamma = \psi_0 + \psi_1\omega + \psi_2\omega^2 \in F_3$, $\rho_j(\gamma) = \psi_0 + \cdots + \psi_{j-1}\omega^{j-1}$ for $j = 1, 2, 3$, where $\psi_b \in \Psi_{b+1}, b = 0, 1, 2$. Let

$$D_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & x \\ 0 & x & x+1 \\ 0 & x+1 & 1 \end{pmatrix}, \qquad D_2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & \omega & 2\omega \\ 0 & 2\omega & \omega \end{pmatrix},$$

$$D_3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & \omega^2 \\ 0 & \omega^2 & 0 \\ 0 & \omega^2 & \omega^2 \end{pmatrix}.$$

Then

$$E_1 = D_1, \qquad E_2 = D_2 \oplus_c D_1, \qquad E_3 = D_3 \oplus_c D_2 \oplus_c D_1,$$

$$\Delta_l^1 = E_3([4(l-1)+1]:4l), \qquad l = 1, \ldots, 12, \text{ and}$$

$$\Delta_l^2 = E_3([12(l-1)+1]:12l), \qquad l = 1, \ldots, 4,$$

which are listed in Table 3.

It can be verified that:

(i) $(E_1, E_2, E_3; \rho_1, \rho_2, \rho_3)$ is an NDM with three layers, where $\rho_j(E_i)$'s are difference matrices: $\rho_1(E_1) = E_1$, $\rho_1(E_2) = (E_1', E_1', E_1')'$, $\rho_2(E_2) = E_2$, $\rho_1(E_3) = \underbrace{(E_1', \ldots, E_1')'}_{12}$, $\rho_2(E_3) = (E_2', E_2', E_2', E_2')'$ and $\rho_3(E_3) = E_3$;

(ii) $\rho_1(\Delta_l^1) = E_1$ for $l = 1, \ldots, 12$, $\rho_1(\Delta_l^2) = (E_1', E_1', E_1')'$ for $l = 1, \ldots, 4$, $\rho_2(\Delta_l^2) = E_2$ for $l = 1, \ldots, 4$, which are all difference matrices.

REMARK 4. Theorem 4 provides a method for constructing NOAs and SOAs from NDMs. The method can also be applied to generate NOAs and SOAs using the NDMs obtained in Theorem 6 in a similar fashion and the details are omitted.

7. Generation of space-filling designs from NOAs and SOAs. We now discuss procedures for using the constructed NOAs and SOAs to generate NSFDs

TABLE 3

The array E_3 in Example 3, where $E_1 = E_3(1:4)$, $E_2 = E_3(1:12)$, $\Delta_l^1 = E_3([4(l-1)+1]:4l)$ for $l = 1, \ldots, 12$, and $\Delta_l^2 = E_3([12(l-1)+1]:12l)$ for $l = 1, \ldots, 4$

Row	x_1	x_2	x_3	Row	x_1	x_2	x_3
1	0	0	0	25	0	ω^2	0
2	0	1	x	26	0	ω^2+1	x
3	0	x	$x+1$	27	0	ω^2+x	$x+1$
4	0	$x+1$	1	28	0	ω^2+x+1	1
5	0	ω	2ω	29	0	$\omega^2+\omega$	2ω
6	0	$\omega+1$	$2\omega+x$	30	0	$\omega^2+\omega+1$	$2\omega+x$
7	0	$\omega+x$	$2\omega+x+1$	31	0	$\omega^2+\omega+x$	$2\omega+x+1$
8	0	$\omega+x+1$	$2\omega+1$	32	0	$\omega^2+\omega+x+1$	$2\omega+1$
9	0	2ω	ω	33	0	$\omega^2+2\omega$	ω
10	0	$2\omega+1$	$\omega+x$	34	0	$\omega^2+2\omega+1$	$\omega+x$
11	0	$2\omega+x$	$\omega+x+1$	35	0	$\omega^2+2\omega+x$	$\omega+x+1$
12	0	$2\omega+x+1$	$\omega+1$	36	0	$\omega^2+2\omega+x+1$	$\omega+1$
13	0	0	ω^2	37	0	ω^2	ω^2
14	0	1	ω^2+x	38	0	ω^2+1	ω^2+x
15	0	x	ω^2+x+1	39	0	ω^2+x	ω^2+x+1
16	0	$x+1$	ω^2+1	40	0	ω^2+x+1	ω^2+1
17	0	ω	$\omega^2+2\omega$	41	0	$\omega^2+\omega$	$\omega^2+2\omega$
18	0	$\omega+1$	$\omega^2+2\omega+x$	42	0	$\omega^2+\omega+1$	$\omega^2+2\omega+x$
19	0	$\omega+x$	$\omega^2+2\omega+x+1$	43	0	$\omega^2+\omega+x$	$\omega^2+2\omega+x+1$
20	0	$\omega+x+1$	$\omega^2+2\omega+1$	44	0	$\omega^2+\omega+x+1$	$\omega^2+2\omega+1$
21	0	2ω	$\omega^2+\omega$	45	0	$\omega^2+2\omega$	$\omega^2+\omega$
22	0	$2\omega+1$	$\omega^2+\omega+x$	46	0	$\omega^2+2\omega+1$	$\omega^2+\omega+x$
23	0	$2\omega+x$	$\omega^2+\omega+x+1$	47	0	$\omega^2+2\omega+x$	$\omega^2+\omega+x+1$
24	0	$2\omega+x+1$	$\omega^2+\omega+1$	48	0	$\omega^2+2\omega+x+1$	$\omega^2+\omega+1$

and SSFDs, respectively. Without loss of generality, we consider generating space-filling designs from the NOAs and SOAs in Theorem 1. Similar procedures can be carried out for other NOAs and SOAs.

7.1. *Generation of NSFDs.* Qian, Tang and Wu (2009) proposed a method for generating NSFDs from NOAs with two layers and we extend their idea to generate NSFDs with more than two layers. We first introduce the definition of nested permutation with I layers [Qian (2009)]. Let $Z_{s_I} = \{0, 1, \ldots, s_I - 1\}$, we call $\pi_{np} = (\pi_{np}(1), \ldots, \pi_{np}(s_I))$ a *nested permutation* with I layers on Z_{s_I}, if the s_i elements of $(\lfloor \pi_{np}(1)s_i/s_I \rfloor, \ldots, \lfloor \pi_{np}(s_i)s_i/s_I \rfloor)$ is a permutation on $Z_{s_i} = \{0, 1, \ldots, s_i - 1\}$ for $i = 1, \ldots, I$, where $\lfloor z \rfloor$ denotes the largest integer no larger than z [Qian (2009)]. Note that a necessary and sufficient condition for a π_{np} to be a nest permutation is that precisely one of its first s_i entries falls within each of the s_i sets defined by $\{0, \ldots, s_I/s_i - 1\}, \{s_I/s_i, \ldots, 2s_I/s_i - 1\}, \ldots, \{(s_i - 1)s_I/s_i, \ldots, s_I - 1\}$

for $i = 1, \ldots, I$. Qian (2009) presented an algorithm for generating nested permutations with I layers on $\{1, 2, \ldots, s_I\}$, which can be modified to generate nested permutations with I layers on Z_{s_I}, using the same uniform permutations as in Qian (2009). Now we propose an algorithm using this type of permutation to relabel the levels of A_I and then obtain an NSFD.

ALGORITHM 3.   *Step* 1. Take an NOA $(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$ from Theorem 1 and let π_{np}^l be a nested permutation with I layers on Z_{s_I}, $l = 1, \ldots, (p^k - 1)/(p - 1)$.

Step 2. Relabel the levels of the lth column of A_I according to $\widetilde{V}(r) \longrightarrow \pi_{\mathrm{np}}^l(r)$ for $r = 1, \ldots, s_I$, and $l = 1, \ldots, (p^k - 1)/(p - 1)$, where $\widetilde{V} = (\widetilde{V}(r)) = V_{T_I} \oplus V_{T_{I-1}} \oplus \cdots \oplus V_{T_1}$ [note that $\widetilde{V}$ is different from the V_{F_I} defined in (4)]. Let M_I be the resulting matrix.

Step 3. Obtain an OA-based Latin hypercube L_I from M_I.

Step 4. Take L_i to be the submatrix of L_I consisting of the first s_i^k rows given by $L_i = L_I(1 : s_i^k)$, for $i = 1, \ldots, I - 1$.

THEOREM 7.   *The $(L_1, \ldots, L_I)$ is an NSFD with I layers, where L_i not only achieves stratification in any one dimension, but also achieves stratification on the $s_i \times s_i$ grids in any two dimensions for $i = 1, \ldots, I$.*

PROOF.   Note that $\rho_j(A_i)$ is an $OA(s_i^k, (p^k - 1)/(p - 1), s_j, 2)$ and the entries of F_i are relabeled with the first s_i entries of π_{np}^l, where precisely one of these first s_i entries falls within each of the s_i sets defined by $\{0, \ldots, s_I/s_i - 1\}, \{s_I/s_i, \ldots, 2s_I/s_i - 1\}, \ldots, \{(s_i - 1)s_I/s_i, \ldots, s_I - 1\}$, $1 \leq j \leq i \leq I$ and $l = 1, \ldots, (p^k - 1)/(p - 1)$. The conclusions now follow.   □

EXAMPLE 4 (Example 1 continued).   Generate three nested permutations with three layers $\pi_{\mathrm{np}}^1 = (4, 1, 2, 7, 6, 5, 3, 0)$, $\pi_{\mathrm{np}}^2 = (5, 2, 0, 7, 3, 4, 1, 6)$, and $\pi_{\mathrm{np}}^3 = (2, 6, 1, 4, 3, 5, 7, 0)$ on $Z_8 = \{0, \ldots, 7\}$. Note that precisely one of the first 2^i entries of π_{np}^l falls within each of the 2^i sets defined by $\{0, \ldots, 2^{3-i} - 1\}, \{2^{3-i}, \ldots, 2 \times 2^{3-i} - 1\}, \ldots, \{(2^i - 1)2^{3-i}, \ldots, 2^3 - 1\}$, $i, l = 1, 2, 3$. Relabel the levels of the lth column of A_3 according to $\widetilde{V}(r) \longrightarrow \pi_{\mathrm{np}}^l(r), r = 1, \ldots, 8, l = 1, 2, 3$, where $\widetilde{V} = (0, 1, x, x + 1, x^2, x^2 + 1, x^2 + x, x^2 + x + 1)'$. The resulting matrix M_3 is given in Table 4. Use M_3 to obtain an OA-based Latin hypercube L_3 listed in Table 5, and take L_1 and L_2 to be the first four and sixteen rows of L_3, respectively. The bivariate projections among x_1, x_2, x_3 of L_3 are plotted in Figure 2, where the symbols "$*$", "$+$" and "$\diamondsuit$" denote the points in L_1, $L_2 \setminus L_1$ and $L_3 \setminus L_2$, respectively. The figure indicates that L_i achieves stratification on the $2^i \times 2^i$ grids in any two dimensions for $i = 1, 2, 3$.

TABLE 4

M₃ in Example 4

Row	x_1	x_2	x_3	Row	x_1	x_2	x_3
1	4	5	2	33	6	5	3
2	4	2	6	34	6	2	5
3	1	5	6	35	5	5	5
4	1	2	2	36	5	2	3
5	4	0	1	37	6	0	7
6	4	7	4	38	6	7	0
7	1	0	4	39	5	0	0
8	1	7	1	40	5	7	7
9	2	5	1	41	3	5	7
10	2	2	4	42	3	2	0
11	7	5	4	43	0	5	0
12	7	2	1	44	0	2	7
13	2	0	2	45	3	0	3
14	2	7	6	46	3	7	5
15	7	0	6	47	0	0	5
16	7	7	2	48	0	7	3
17	4	3	3	49	6	3	2
18	4	4	5	50	6	4	6
19	1	3	5	51	5	3	6
20	1	4	3	52	5	4	2
21	4	1	7	53	6	1	1
22	4	6	0	54	6	6	4
23	1	1	0	55	5	1	4
24	1	6	7	56	5	6	1
25	2	3	7	57	3	3	1
26	2	4	0	58	3	4	4
27	7	3	0	59	0	3	4
28	7	4	7	60	0	4	1
29	2	1	3	61	3	1	2
30	2	6	5	62	3	6	6
31	7	1	5	63	0	1	6
32	7	6	3	64	0	6	2

7.2. *Generation of SSFDs.*   Qian and Wu (2009) proposed a method to obtain SSFDs from SOAs. Here we present a more flexible procedure that can use the SOAs constructed in Sections 4–6 to generate a new class of SSFDs. Without loss of generality, consider the SOAs constructed in Theorem 1.

ALGORITHM 4.   *Step* 1. Choose the values of i, j, I, where $1 \leq j \leq i \leq I$. Suppose A_I and $(\Gamma_1^i, \ldots, \Gamma_{(s_I/s_i)^k}^i; \rho_j)$ are constructed in Theorem 1. Relabel the s_I levels of A_I as $0, \ldots, s_I - 1$ according to the following two stages:

TABLE 5

L_3 in Example 4, where $L_1 = L_3(1:4)$, $L_2 = L_3(1:16)$

Row	x_1	x_2	x_3	Row	x_1	x_2	x_3
1	39	44	17	33	51	47	28
2	38	19	49	34	52	17	41
3	12	40	50	35	44	46	42
4	13	18	21	36	46	21	24
5	34	7	8	37	54	2	62
6	33	58	33	38	49	62	7
7	10	5	39	39	43	0	0
8	11	61	14	40	40	59	58
9	22	41	9	41	24	42	60
10	19	20	34	42	25	22	2
11	60	45	36	43	2	43	1
12	59	16	15	44	6	23	61
13	23	4	23	45	30	1	30
14	17	60	51	46	29	56	43
15	61	3	52	47	5	6	40
16	58	57	20	48	4	63	26
17	35	28	27	49	53	31	16
18	36	32	45	50	50	38	53
19	8	25	46	51	47	27	48
20	14	35	29	52	41	36	22
21	32	9	63	53	55	13	10
22	37	52	3	54	48	48	35
23	9	15	6	55	45	11	37
24	15	51	59	56	42	50	13
25	16	30	56	57	27	24	12
26	20	37	4	58	26	39	38
27	62	26	5	59	3	29	32
28	57	33	57	60	7	34	11
29	18	8	31	61	28	10	19
30	21	49	47	62	31	55	55
31	56	14	44	63	1	12	54
32	63	53	25	64	0	54	18

(i) Use the projection ρ_j defined in (8) to divide the s_I levels into s_j groups

$$\Phi_\alpha^j = \{\gamma | \rho_j(\gamma) = \alpha, \gamma \in F_I\} \qquad \text{for } \alpha \in F_j,$$

each of size $q = s_I/s_j$.

(ii) Arbitrarily label the s_j groups as groups $1, \ldots, s_j$, and label the q levels within the gth group as $(g-1)q, (g-1)q+1, \ldots, gq-1$, for $g = 1, \ldots, s_j$. This relabeling scheme can be denoted by

(15) $$\{\Phi_\alpha^j | \alpha \in F_j\} \longrightarrow \Lambda^j = \{\Lambda_g^j | g = 1, \ldots, s_j\},$$
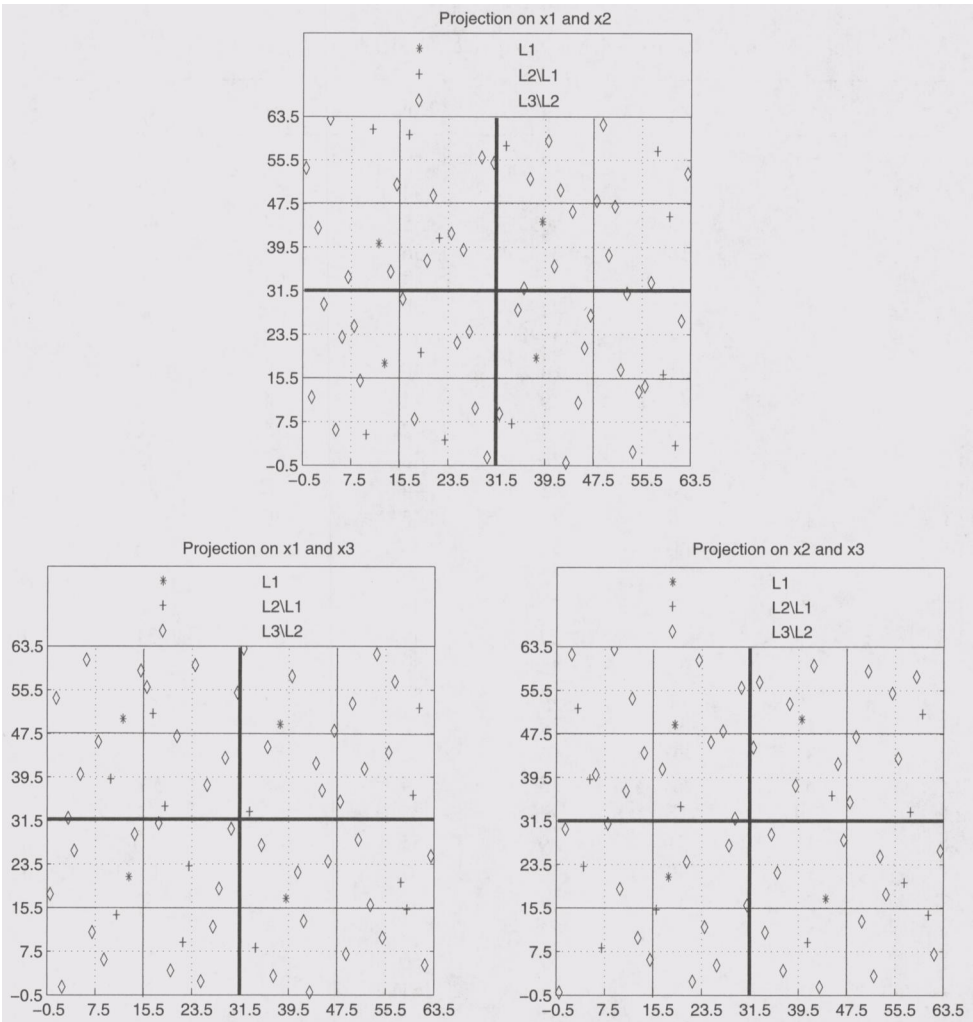
FIG. 2. *Bivariate projections among x_1, x_2, x_3 of L_3 in Example 4.*

where $\Lambda_g^j = \{(g-1)q, (g-1)q+1, \ldots, gq-1 | q = s_I/s_j\}$.

Step 2. Let M be the design obtained by relabeling the levels of A_I, and use M to obtain an OA-based Latin hypercube S.

Step 3. Partition S into $(s_I/s_i)^k$ subarrays corresponding to $\Gamma_1^i, \ldots, \Gamma_{(s_I/s_i)^k}^i$, that is, $S = (S_1', \ldots, S_{(s_I/s_i)^k}')'$ with $S_l = S([(l-1)s_i^k+1]:ls_i^k), l = 1, \ldots, (s_I/s_i)^k$.

THEOREM 8. *For* $S = (S_1', \ldots, S_{(s_I/s_i)^k}')'$ *constructed in Algorithm* 4, S *achieves stratification on the $s_I \times s_I$ grids in any two dimensions, and S_l achieves stratification on the $s_j \times s_j$ grids in any two dimensions for $l = 1, \ldots, (s_I/s_i)^k$.*

Thus, $S = (S_1', \ldots, S_{(s_I/s_i)^k}')'$ is an SSFD with $(s_I/s_i)^k$ slices.

PROOF. By noting that A_I and $\rho_j(\Gamma_l^i)$ for $l = 1, \ldots, (s_I/s_i)^k$ are all orthogonal arrays of strength two, and following the relabeling scheme given above, the conclusions hold. $\square$

EXAMPLE 5 (Example 1 continued). (i) For $i = j = 1$, we have $q = 4$, $\Phi_0^1 = \{\gamma | \rho_1(\gamma) = 0, \gamma \in F_3\} = \{0, x^2, x, x^2 + x\}$, $\Phi_1^1 = \{1, x^2 + 1, x + 1, x^2 + x + 1\}$, $\Lambda_1^1 = \{0, 1, 2, 3\}$ and $\Lambda_2^1 = \{4, 5, 6, 7\}$. Arbitrarily relabel the levels of A_3 in Table 1 according to the scheme given in Step 1 as follows:

$$\{\{0, x^2, x, x^2 + x\}, \{1, x^2 + 1, x + 1, x^2 + x + 1\}\} \longrightarrow \{\{0, 1, 2, 3\}, \{4, 5, 6, 7\}\},$$

and then obtain an OA-based Latin hypercube S. Let $S_l = S([4(l-1)+1]:4l), l = 1, \ldots, 16$. Note that S achieves stratification on the 8×8 grids in any two dimensions, S_l achieves stratification on the 2×2 grids in any two dimensions, and $S = (S_1', \ldots, S_{16}')'$ is an SSFD with 16 slices.

(ii) For $i = j = 2$, we have $q = 2$, $\Phi_0^2 = \{0, x^2\}$, $\Phi_x^2 = \{x, x^2 + x\}$, $\Phi_1^2 = \{1, x^2 + 1\}$, $\Phi_{x+1}^2 = \{x + 1, x^2 + x + 1\}$, $\Lambda_1^2 = \{0, 1\}$, $\Lambda_2^2 = \{2, 3\}$, $\Lambda_3^2 = \{4, 5\}$ and $\Lambda_4^2 = \{6, 7\}$. Relabel the levels of A_3 according to

$$\{\{0, x^2\}, \{x, x^2 + x\}, \{1, x^2 + 1\}, \{x + 1, x^2 + x + 1\}\}$$
$$\longrightarrow \{\{0, 1\}, \{2, 3\}, \{4, 5\}, \{6, 7\}\},$$

to obtain an OA-based Latin hypercube $S = (S_1', \ldots, S_4')'$, where $S_l = S([16(l-1)+1]:16l), l = 1, \ldots, 4$. Similarly, S achieves stratification on the 8×8 grids in any two dimensions, S_l achieves stratification on the 4×4 grids in any two dimensions, and $S = (S_1', \ldots, S_4')'$ is an SSFD with 4 slices.

REMARK 5. If we relabel the levels of A_3 according to

(16)
$$\{\{0, x^2\}, \{x, x^2 + x\}\} \longrightarrow \{\{0, 1\}, \{2, 3\}\} \quad \text{and}$$
$$\{\{1, x^2 + 1\}, \{x + 1, x^2 + x + 1\}\} \longrightarrow \{\{4, 5\}, \{6, 7\}\},$$

in Example 5, then by Theorem 8, we have:

(a) S can be partitioned into 16 slices, $S([4(l-1)+1]:4l)$ for $l = 1, \ldots, 16$, each of which achieves stratification on the 2×2 grids in any two dimensions;

(b) S can be partitioned into 4 slices, $S([16(l-1)+1]:16l)$ for $l = 1, \ldots, 4$, each of which achieves stratification on the 4×4 grids in any two dimensions;

(c) S achieves stratification on the 8×8 grids in any two dimensions;

(d) S is an SSFD that can be sliced into 4 or 16 slices.

Therefore, under the same relabel scheme (16), S can be used to conduct computer experiments with qualitative factors of 4 and 16 distinct level combinations, respectively. A further discussion on S will be found in Example 6.

Inspired by Remark 5, we now propose a new construction of SSFDs from SOAs which can generate SSFDs with different numbers of slices simultaneously. A new permutation is needed. We call $\pi_{sp} = (\pi_{sp}(1), \ldots, \pi_{sp}(s_I))$ a *sliced permutation* with I layers on Z_{s_I}, if

$$\{\pi_{sp}((g-1)q+1), \pi_{sp}((g-1)q+2), \ldots, \pi_{sp}(gq)\} \in \Lambda^j$$

for $j = 1, \ldots, I-1$, $g = 1, \ldots, s_j$ and $q = s_I/s_j$, where Λ^j is defined in (15).

ALGORITHM 5. *Step* 1. Suppose A_I is constructed in Theorem 1 and π_{sp}^l is a sliced permutation with I layers on Z_{s_I}, $l = 1, \ldots, (p^k - 1)/(p - 1)$.

Step 2. Relabel the levels of the lth column of A_I according to $V_{F_I}(r) \longrightarrow \pi_{sp}^l(r)$ for $r = 1, \ldots, s_I$, and $l = 1, \ldots, (p^k - 1)/(p - 1)$, where $V_{F_I} = V_{T_1} \oplus V_{T_2} \oplus \cdots \oplus V_{T_I}$ defined in (4). Let M be the resulting matrix.

Step 3. Obtain an OA-based Latin hypercube S from M.

Step 4. For $i = 1, \ldots, I-1$, partition S into $(s_I/s_i)^k$ subarrays with an equal number of rows, that is, $S = ((S_1^i)', \ldots, (S_{(s_I/s_i)^k}^i)')'$ with $S_l^i = S([(l-1)s_i^k + 1] : ls_i^k)$ for $l = 1, \ldots, (s_I/s_i)^k$.

THEOREM 9. *For* $S = ((S_1^i)', \ldots, (S_{(s_I/s_i)^k}^i)')'$ *constructed in Algorithm* 5, S_l^i *achieves stratification on the* $s_j \times s_j$ *grids in any two dimensions, for* $l = 1, \ldots, (s_I/s_i)^k$ *and* $1 \le j \le i \le I$. *Thus,* $S = ((S_1^i)', \ldots, (S_{(s_I/s_i)^k}^i)')'$ *is an SSFD with* $(s_I/s_i)^k$ *slices, for* $i = 1, \ldots, I-1$.

PROOF. For any $\alpha \in F_I$, let α_l denote the corresponding element in π_{sp}^l under the relabeling $V_{F_I} \longrightarrow \pi_{sp}^l$, $l = 1, \ldots, (p^k - 1)/(p - 1)$. Since A_I and $\rho_j(\Gamma_I^i)$ for $l = 1, \ldots, (s_I/s_i)^k$ and $1 \le j \le i \le I - 1$ are all orthogonal arrays of strength two, it suffices to prove that for any $\alpha, \beta \in F_j$ with $\alpha \neq \beta$, α_l and β_l fall in different sets defined by $\{0, 1, \ldots, q-1\}, \{q, q+1, \ldots, 2q-1\}, \ldots, \{(s_j-1)q, (s_j-1)q + 1, \ldots, s_jq-1\}$, where $q = s_I/s_j$. Note that $V_{F_I} = V_{T_1} \oplus V_{T_2} \oplus \cdots \oplus V_{T_I} = V_{F_j} \oplus (V_{T_{j+1}} \oplus \cdots \oplus V_{T_I})$ and the first element of V_{T_i} is 0, $i = 1, \ldots, I$, then $\alpha, \beta \in \{V_{F_I}(g)|g = 1, q+1, 2q+1, \ldots, (s_j-1)q+1\}$. Suppose $\alpha = V_{F_I}(c_1q+1)$, $\beta = V_{F_I}(c_2q+1)$, $c_1, c_2 = 0, 1, \ldots, s_j - 1$, and $c_1 \neq c_2$. Then $\alpha_l = \pi_{sp}^l(c_1q+1)$ and $\beta_l = \pi_{sp}^l(c_2q+1)$ and, therefore, $\alpha_l \in \Lambda_{d_1}^j$, $\beta_l \in \Lambda_{d_2}^j$ for some $d_1, d_2 = 1, 2, \ldots, s_j$ and $d_1 \neq d_2$ (this is because $|(c_1q+1) - (c_2q+1)| = |(c_1 - c_2)q| \ge q$), and α_l and β_l fall in different sets defined by $\{0, 1, \ldots, q-1\}, \{q, q+1, \ldots, 2q-1\}, \ldots, \{(s_j-1)q, (s_j-1)q + 1, \ldots, s_jq-1\}$. $\square$

EXAMPLE 6 (Example 1 continued). Generate three sliced permutations with three layers $\pi_{sp}^1 = (0, 1, 2, 3, 7, 6, 5, 4)$, $\pi_{sp}^2 = (7, 6, 5, 4, 1, 0, 2, 3)$ and $\pi_{sp}^3 = (0, 1, 3, 2, 4, 5, 7, 6)$ on Z_8. Note that

$$\{\pi_{sp}^l(r2^{3-j} + 1), \ldots, \pi_{sp}^l((r+1)2^{3-j})\} \in \Lambda^j$$
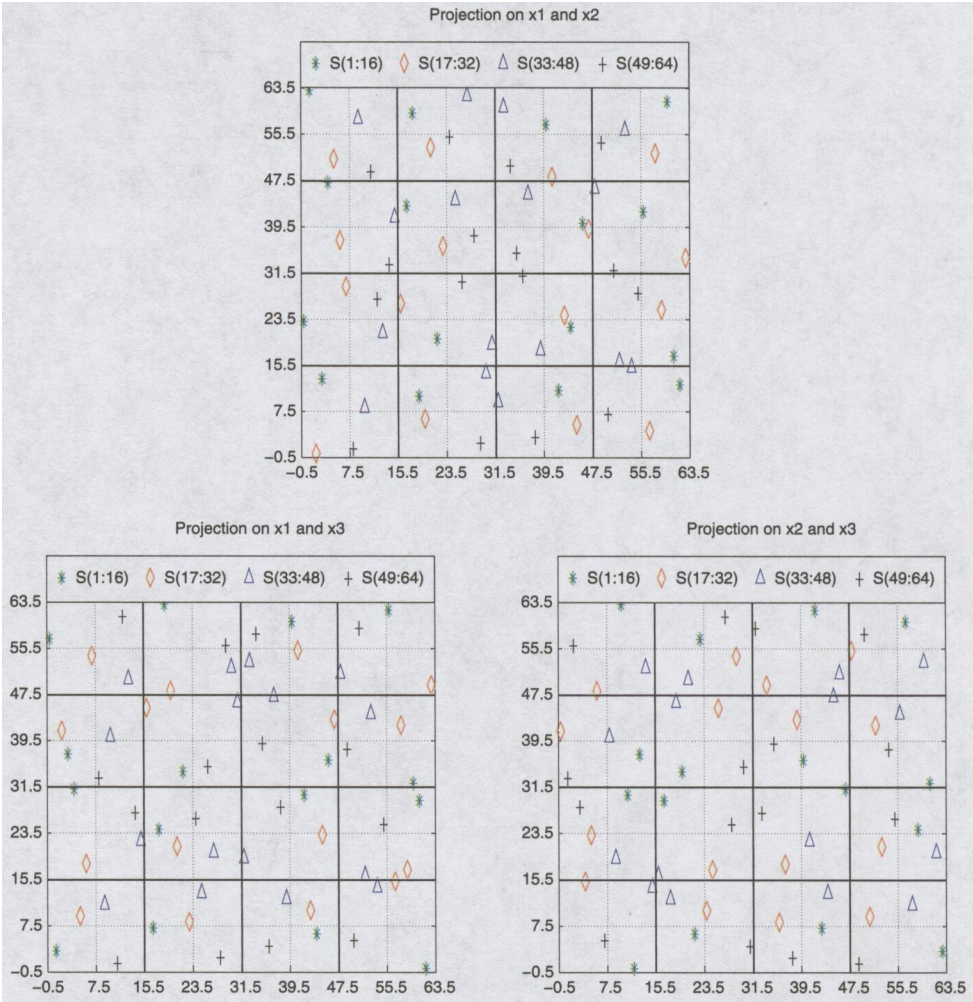
FIG. 3. *Bivariate projections among x_1, x_2 and x_3 of S in Example 6.*

for $r = 0, 1, \ldots, 2^j - 1$ and $j = 1, 2$, where $\Lambda^1 = \{\{0, 1, 2, 3\}, \{4, 5, 6, 7\}\}$ and $\Lambda^2 = \{\{0, 1\}, \{2, 3\}, \{4, 5\}, \{6, 7\}\}$. Relabel the levels of the lth column of A_3 according to $V_{F_I}(r) \longrightarrow \pi_{\text{sp}}^l(r), r = 1, \ldots, 8, l = 1, 2, 3$, where $V_{F_I} = \{0, x^2, x, x + x^2, 1, x^2 + 1, x + 1, x + x^2 + 1\}$. Denote the resulting matrix by M in Table 6, and use M to obtain an OA-based Latin hypercube S given in columns x_1, x_2 and x_3 in Table 8. Note that $S([4^i(l-1)+1]:4^i l)$ achieves stratification on the $2^i \times 2^i$ grids in any two dimensions for $l = 1, 2, \ldots, 4^{3-i}$ and $i = 1, 2$; see Figure 3 for an illustration, where for brevity, we only plot the bivariate projections of $S([16(l-1)+1]:16l)$ for $l = 1, \ldots, 4$.

The design in Table 8 consists of two parts: the SSFD S (columns x_1, x_2, x_3) obtained in Example 6 for arranging quantitative factors, and an $OA(16, 2^3 4^3)$ with

TABLE 6

The array M in Example 6

Row	x_1	x_2	x_3	Row	x_1	x_2	x_3
1	0	7	0	33	1	7	1
2	0	1	4	34	1	1	5
3	7	7	4	35	6	7	5
4	7	1	0	36	6	1	1
5	0	5	3	37	1	5	2
6	0	2	7	38	1	2	6
7	7	5	7	39	6	5	6
8	7	2	3	40	6	2	2
9	2	7	3	41	3	7	2
10	2	1	7	42	3	1	6
11	5	7	7	43	4	7	6
12	5	1	3	44	4	1	2
13	2	5	0	45	3	5	1
14	2	2	4	46	3	2	5
15	5	5	4	47	4	5	5
16	5	2	0	48	4	2	1
17	0	6	1	49	1	6	0
18	0	0	5	50	1	0	4
19	7	6	5	51	6	6	4
20	7	0	1	52	6	0	0
21	0	4	2	53	1	4	3
22	0	3	6	54	1	3	7
23	7	4	6	55	6	4	7
24	7	3	2	56	6	3	3
25	2	6	2	57	3	6	3
26	2	0	6	58	3	0	7
27	5	6	6	59	4	6	7
28	5	0	2	60	4	0	3
29	2	4	1	61	3	4	0
30	2	3	5	62	3	3	4
31	5	4	5	63	4	4	4
32	5	3	1	64	4	3	0

replicate runs (the last six columns) for arranging qualitative factors, where the original $OA(16, 2^3 4^3)$ is listed in Table 7. Note that S possesses properties: (i) if S is partitioned into 4 slices with 16 runs in each slice, then each slice achieves stratification on the 4×4 grids in any two dimensions; (ii) if S is partitioned into 16 slices with 4 runs in each slice, then each slice achieves stratification on the 2×2 grids in any two dimensions. Therefore, for the design in Table 8, (i) for any level combination of the three two-level qualitative factors, the design points for the quantitative factors achieve stratification on the 4×4 grids in any two dimensions; (ii) for any level combination of the three four-level qualitative factors, the design

TABLE 7

$OA(16, 2^3 4^3, 2)$

1	2	3	4	5	6
0	0	0	0	0	0
0	0	0	0	3	3
0	0	0	3	1	2
0	0	0	3	2	1
0	1	1	2	0	2
0	1	1	2	3	1
0	1	1	1	2	3
0	1	1	1	1	0
1	0	1	2	2	0
1	0	1	2	1	3
1	0	1	1	0	1
1	0	1	1	3	2
1	1	0	0	2	2
1	1	0	0	1	1
1	1	0	3	0	3
1	1	0	3	3	0

points for the quantitative factors achieve stratification on the 2×2 grids in any two dimensions; (iii) it possesses good space-filling properties when collapsed over the qualitative factors. Hence, the design in Table 8 is suitable for conducting a computer experiment with three quantitative factors and six qualitative factors, where three of them have 2 levels and another three have 4 levels.

We have provided some new constructions of NSFDs and SSFDs based on NOAs and SOAs of strength two, respectively. Better NSFDs and SSFDs can be obtained by using NOAs and SOAs with strength greater than two. See Remarks 1 and 2, Theorems 3 and 5 and Corollary 2.

8. Comparisons and concluding remarks. The families of NSFDs constructed by the existing methods are limited to two layers, with the exception of Haaland and Qian (2010). The method of Haaland and Qian (2010) is based on the infinite (t, s)-sequences which are more difficult to obtain than the orthogonal arrays used in our methods. Here are some comparisons between our methods and the existing constructions.

Qian, Tang and Wu (2009) (QTW) and Qian, Ai and Wu (2009) (QAW) presented several methods for constructing NSFDs with two layers from NOAs and NDMs. NSFDs with more than two layers cannot be constructed by using their methods. The technical reason is that the modulus projection used in Qian, Tang and Wu (2009) cannot be extended to covering more than two layers, as argued in Section 3.2. The subgroup projection presented in this paper is different and

TABLE 8

Design with qualitative and quantitative factors, where columns x_1, x_2, x_3 are quantitative ones, x_4, x_5, x_6 are 2-level qualitative ones, and x_7, x_8, x_9 are 4-level qualitative ones

Row	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9
1	1	63	3	0	0	0	0	0	0
2	3	13	37	0	0	0	0	0	0
3	60	61	32	0	0	0	0	0	0
4	62	12	0	0	0	0	0	0	0
5	4	47	31	0	0	0	0	3	3
6	0	23	57	0	0	0	0	3	3
7	56	42	62	0	0	0	0	3	3
8	61	17	29	0	0	0	0	3	3
9	18	59	24	0	0	0	3	1	2
10	19	10	63	0	0	0	3	1	2
11	40	57	60	0	0	0	3	1	2
12	42	11	30	0	0	0	3	1	2
13	17	43	7	0	0	0	3	2	1
14	22	20	34	0	0	0	3	2	1
15	46	40	36	0	0	0	3	2	1
16	44	22	6	0	0	0	3	2	1
17	5	51	9	0	1	1	2	0	2
18	2	0	41	0	1	1	2	0	2
19	58	52	42	0	1	1	2	0	2
20	57	4	15	0	1	1	2	0	2
21	6	37	18	0	1	1	2	3	1
22	7	29	54	0	1	1	2	3	1
23	63	34	49	0	1	1	2	3	1
24	59	25	17	0	1	1	2	3	1
25	21	53	21	0	1	1	1	2	3
26	20	6	48	0	1	1	1	2	3
27	41	48	55	0	1	1	1	2	3
28	45	5	23	0	1	1	1	2	3
29	23	36	8	0	1	1	1	1	0
30	16	26	45	0	1	1	1	1	0
31	47	39	43	0	1	1	1	1	0
32	43	24	10	0	1	1	1	1	0
33	9	58	11	1	0	1	2	2	0
34	10	8	40	1	0	1	2	2	0
35	53	56	44	1	0	1	2	2	0
36	54	15	14	1	0	1	2	2	0
37	15	41	22	1	0	1	2	1	3
38	13	21	50	1	0	1	2	1	3
39	48	46	51	1	0	1	2	1	3
40	52	16	16	1	0	1	2	1	3
41	27	62	20	1	0	1	1	0	1
42	30	14	52	1	0	1	1	0	1
43	33	60	53	1	0	1	1	0	1
44	32	9	19	1	0	1	1	0	1

TABLE 8
(*Continued*)

Row	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9
45	25	44	13	1	0	1	1	3	2
46	31	19	46	1	0	1	1	3	2
47	37	45	47	1	0	1	1	3	2
48	39	18	12	1	0	1	1	3	2
49	11	49	1	1	1	0	0	2	2
50	8	1	33	1	1	0	0	2	2
51	49	54	38	1	1	0	0	2	2
52	50	7	5	1	1	0	0	2	2
53	14	33	27	1	1	0	0	1	1
54	12	27	61	1	1	0	0	1	1
55	51	32	59	1	1	0	0	1	1
56	55	28	25	1	1	0	0	1	1
57	24	55	26	1	1	0	3	0	3
58	29	2	56	1	1	0	3	0	3
59	34	50	58	1	1	0	3	0	3
60	38	3	28	1	1	0	3	0	3
61	28	38	2	1	1	0	3	3	0
62	26	30	35	1	1	0	3	3	0
63	35	35	39	1	1	0	3	3	0
64	36	31	4	1	1	0	3	3	0

more general, and it has been used to generate more NSFDs which can accommodate nesting with an arbitrary number of layers and are more flexible in run size. Qian and Ai (2010) (QA) proposed some construction methods for NOAs and NDMs with two layers based on Galois fields and incomplete pairwise orthogonal Latin squares. Qian (2009) presented a method for constructing nested Latin hypercube designs, but the resulting designs can achieve stratification only in one dimension. Thus, we only present the comparisons among QTW, QAW, QA and our proposed methods (SLQ). The comparison among QAW, QA and SLQ for the construction of NDMs with two layers, and the comparison among QTW, QAW, QA and SLQ for the construction of NOAs with two layers, are listed in Tables 9 and 10, respectively. Since the construction of incomplete pairwise orthogonal Latin squares is still an open problem, thus we only tabulate the results obtained based on Galois fields in QA. In addition, QAW and the present paper presented several indirect methods to obtain NOAs based on existing NOAs or NDMs, for example, Theorems 4, 5 in QAW and Theorem 4 in the present paper. In Tables 9 and 10, we only tabulate the NOAs and NDMs that can be directly constructed. Moreover, Tables 11 and 12 tabulate some construction results of the proposed methods for designs with more than two layers.

TABLE 9

Comparisons among the NDM(D_1, D; ρ_1, ρ_2)'s constructed by QAW, QA and SLQ

Methods		$\rho_1(D_1)$	D	Constraints*
QAW	I	$D(p^m, p^2, p^m)$	$D(p^{m+1}, p^2, p^{m+1})$	$m \geq 2$
	II	$D(p^m, p^2, p^m)$	$D(p^{m+2}, p^2, p^{m+2})$	$p = 2, 3$
	III	$D(p^{m+1}, p^3, p^m)$	$D(p^{m+2}, p^3, p^{m+2})$	
	IV	$D(p^{m+1}, p^3, p^m)$	$D(p^{m+3}, p^3, p^{m+3})$	
	V	$D(p^{m+2}, p^4, p^m)$	$D(p^{m+3}, p^4, p^{m+3})$	
QA		$D(p^{u_1}, p^{u_1}, p^{u_1})$	$D(p^{u_2}, p^{u_1}, p^{u_2})$	$u_1 < u_2, u_1|u_2$
SLQ	Theorem 4	$D(lp^{u_2}, p^{u_1}, p^{u_2})$	$D(p^{u_3}, p^{u_1}, p^{u_3})$	$u_i|u_{i+1}, i = 1, 2,$ $u_2 < u_3, l < p^{u_3-u_2}$
	Theorem 6	$D(lr_1, c, p^{u_1})$	$D(r_1 r_2, c, p^{u_1+u_2})$	$D(r_i, c, p^{u_i})$ exists, $i = 1, 2, l < r_2$

*p is any prime number.

From these tables and our construction methods, we can see that:

(i) The proposed methods have more flexible choices of the parameters, and thus can generate much more new NDMs and NOAs, hence much more new NSFDs.

TABLE 10

Comparisons among the NOA(A_1, A; ρ_1, ρ_2)'s constructed by QTW, QAW, QA and SLQ

Methods		$\rho_1(A_1)$	A	Constraints*
QTW		$OA(p^{ku_1}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_1}, 2)$	$OA(p^{ku_2}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_2}, 2)$	$2u_1 \leq u_2 + 1$
QAW		$OA(s_1^2, 3, s_1, 2)$	$OA(s_2^2, 3, s_2, 2)$	$s_1 < s_2, s_1|s_2$
QA	I	$OA(p^{ku_1}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_1}, 2)$	$OA(p^{ku_2}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_2}, 2)$	$u_1 < u_2, u_1|u_2$
	II	$OA(p^{ku_1}, p^{u_1}+1, p^{u_1}, k)$	$OA(p^{ku_2}, p^{u_1}+1, p^{u_2}, k)$	$u_1 < u_2, u_1|u_2,$ $p^{u_1} \geq k - 1$
SLQ	Theorem 1	$OA(lp^{ku_1}, \frac{p^k-1}{p-1}, p^{u_1}, 2)$	$OA(p^{ku_2}, \frac{p^k-1}{p-1}, p^{u_2}, 2)$	$l < p^{k(u_2-u_1)},$ $u_1 < u_2$
	Theorem 2	$OA(lp^{ku_1}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_1}, 2)$	$OA(p^{ku_2}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_2}, 2)$	$l < p^{k(u_2-u_1)},$ $u_1 < u_2, u_1|u_2$
	Theorem 3	$OA(lp^{ku_1}, p^{u_1}+1, p^{u_1}, k)$	$OA(p^{ku_2}, p^{u_1}+1, p^{u_2}, k)$	$l < p^{k(u_2-u_1)}, u_1 < u_2,$ $u_1|u_2, p^{u_1} \geq k - 1$
	Theorem 5	$OA(ln_1, m, p^{u_1}, t)$	$OA(n_1 n_2, m, p^{u_1+u_2}, t)$	$OA(n_i, m, p^{u_i}, t)$ exists, $i = 1, 2, l < n_2$

*p is any prime number.

TABLE 11
The $NDM(D_1, \ldots, D_I; \rho_1, \ldots, \rho_I)$'s constructed in this paper for $I > 2$

Methods	$\rho_i(D_i)$, $i = 1, \ldots, I$	Constraints[*]
Theorem 4	$D(p^{u_i}, p^{u_1}, p^{u_i})$	$u_i < u_{i+1}, u_i \| u_{i+1}, i = 1, \ldots, I - 1$
Theorem 6	$D(\prod_{l=1}^{i} r_l, c, p^{\sum_{l=1}^{i} u_l})$	$D(r_i, c, p^{u_i})$ exists, $i = 1, \ldots, I$

[*] p is any prime number.

(ii) For NSFDs with two layers, some of the construction results of QTW, QAW and QA can also be obtained by the proposed methods. For example, in Table 9, by taking $l = 1$, $p = 2, 3$, $u_1 = m$, $u_2 = 2$, $r_1 = p^m$, and $r_2 = c = p^2$, then the NDMs obtained by our Theorem 6 are just those constructed by II of QAW. In addition, most of the NOAs and NDMs obtained by the proposed methods have no overlap with that of QTW, QAW and QA.

(iii) The proposed methods can generate various NDMs and NOAs with more than two layers; see Tables 11 and 12.

(iv) Moreover, the methods for obtaining NOAs can also be used to generate SOAs after some suitable modifications, which are useful for constructing SSFDs for computer experiments with both qualitative and quantitative factors [Qian and Wu (2009)].

The newly proposed methods are easy to implement. The generated NSFDs and SSFDs can be used not only in computer experiments, but also in many other fields as mentioned in Section 1.

TABLE 12
The $NOA(A_1, \ldots, A_I; \rho_1, \ldots, \rho_I)$'s constructed in this paper for $I > 2$

Methods	$\rho_i(A_i)$, $i = 1, \ldots, I$	Constraints[*]
Theorem 1	$OA(p^{ku_i}, \frac{p^k-1}{p-1}, p^{u_i}, 2)$	$u_i < u_{i+1}, i = 1, \ldots, I - 1$
Theorem 2	$OA(p^{ku_i}, \frac{p^{ku_1}-1}{p^{u_1}-1}, p^{u_i}, 2)$	$u_i < u_{i+1}, u_i \| u_{i+1}, i = 1, \ldots, I - 1$
Theorem 3	$OA(p^{ku_i}, p^{u_1} + 1, p^{u_i}, k)$	$p^{u_1} \geq k - 1, u_i < u_{i+1},$ $u_i \| u_{i+1}, i = 1, \ldots, I - 1$
Corollary 2	$OA(\prod_{l=1}^{i} n_l, m, p^{\sum_{l=1}^{i} u_l}, t)$	$OA(n_i, m, p^{u_i}, t)$ exists, $i = 1, \ldots, I$

[*] p is any prime number.

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